Wieler Solenoids from Flat Manifolds Part 1: The Stable Groupoid

NSF

Rachel Chaiser*

University of Colorado Boulder

May 14, 2022

*Joint with Maeve Coates-Welsh, Robin Deeley, Annika Farhner, Jamal Giornozi, Robi Huq, Levi Lorenzo, Jose Oyola-Cortes, Maggie Reardon, Andrew Stocker. Partially supported by NSF grant DMS 2000057.

- Flat manifolds
- Making Smale spaces from flat manifolds
- The stable groupoid $\mathcal{G}^{s}(p)$ and its inductive limit structure
- Morita equivalent groupoids
- K-theory of $C^*(\mathcal{G}^s(p))$
- Unstable Putnam homology via groupoid homology of $\mathcal{G}^{s}(p)$
- Examples
- General results

Flat Manifolds

Definition

A flat manifold Y is a closed connected Riemannian d-manifold with zero curvature.

• $Y \cong \frac{\mathbb{R}^d}{\pi_1(Y)}$ and $\pi_1(Y)$ is a torsionfree group of rigid motions of \mathbb{R}^d Examples:



• There exist finitely many flat manifolds in each dimension

 Dimension
 1
 2
 3
 4
 5

 Number of flat manifolds
 1
 2
 10
 74
 1060

Theorem (Epstein–Shub)

Let Y be a flat manifold. Then there exists a locally expansive surjection $g: Y \rightarrow Y$. Moreover, g is an n-fold cover, $n \ge 2$.

Fix Y, g as above. Using Williams'/Wieler's construction, we get a Smale space (X, φ) :

$$X = \varprojlim(Y,g) = \{(y_n)_{n=0}^{\infty} | y_n \in Y \text{ and } g(y_{n+1}) = y_n\}$$

$$\varphi(y_0, y_1, y_2 \dots) = (g(y_0), g(y_1), g(y_2), \dots) = (g(y_0), y_0, y_1, \dots)$$

$$\varphi^{-1}(y_0, y_1, y_2 \dots) = (y_1, y_2, y_3, \dots)$$

(1) The *n*-solenoid: $Y = S^1 \subseteq \mathbb{C}$ and $g(z) = z^n$.

(2) Let Y = K the Klein bottle and $g : K \to K$ the 9-fold self-cover associated to descending $\begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} : \mathbb{R}^2 \to \mathbb{R}^2$ to K.

The stable groupoid

Recall that for a Smale space (X, φ) we define equivalence relations: (1) stable equivalence: $x \sim_s y$ if $\lim_{n \to \infty} d(\varphi^n(x), \varphi^n(y)) = 0$ (2) unstable equivalence: $x \sim_u y$ if $\lim_{n \to \infty} d(\varphi^{-n}(x), \varphi^{-n}(y)) = 0$ For any $p \in X$ denote $X^u(p) = \{x \in X \mid x \sim_u p\}$.

Theorem (Shub)

 $g: Y \to Y$ has a fixed point z.

• So (X, φ) has a fixed point p = (z, z, z, ...).

Define the stable groupoid for (X, φ) by

$$\mathcal{G}^{s}(p) = \{(x, y) \in X^{u}(p) \times X^{u}(p) \mid x \sim_{s} y\}.$$

Theorem

 $x \sim_s y$ if and only if there exists $k \ge 0$ such that $g^k(x_0) = g^k(y_0)$.

Define a subgroupoid of $\mathcal{G}^{s}(p)$ for each $k \geq 0$

$$\mathcal{G}_k = \left\{ (x, y) \in X^u(p) \times X^u(p) \, \middle| \, g^k(x_0) = g^k(y_0) \right\}.$$

These subgroupoids satisfy:

- $\mathcal{G}_0 \subseteq \mathcal{G}_1 \subseteq \mathcal{G}_2 \subseteq \cdots$ and the inclusions $i_k : \mathcal{G}_k \hookrightarrow \mathcal{G}_{k+1}$ are open
- Each \mathcal{G}_k is étale
- $\mathcal{G}^{s}(p) = \bigcup_{k=0}^{\infty} \mathcal{G}_{k}$
- The inductive limit topology is the usual topology making $\mathcal{G}^{s}(p)$ étale

Morita equivalent groupoids

$$\mathcal{G}_k = \left\{ (x, y) \in X^u(p) \times X^u(p) \, \middle| \, g^k(x_0) = g^k(y_0) \right\}$$

Theorem (Muhley–Renault–Williams)

Let $R \subseteq Z \times Z$ be an equivalence relation on a space Z such that

- (i) the quotient $Z \rightarrow Z/R$ is open;
- (ii) R is closed as a subspace of $Z \times Z$.

Then $R \sim_{M.e.} Z/R$, where Z/R has the groupoid structure of a space.

Each $\mathcal{G}_k \sim_{M.e.} Y$ since

- (i) [DGMW] The projection $\pi_0 : X^u(p) \to Y \cong X^u(p)/\mathcal{G}_0$ defined by $(x, y) \mapsto x_0$ is a cover
- (ii) \mathcal{G}_k is clearly closed in $X^u(p) \times X^u(p)$

Theorem (Muhley–Renault–Williams)

Since $\mathcal{G}_k \sim_{M.e.} Y$, we have $C^*(\mathcal{G}_k) \sim_{M.e.} C(Y)$.

We can compute the K-theory of $C^*(\mathcal{G}^s(p))$ as follows.

$$\begin{split} \mathcal{K}_*(\mathcal{C}^*(\mathcal{G}^s(p))) &\cong \mathcal{K}_*\left(\varinjlim(\mathcal{C}^*(\mathcal{G}_k), i_k)\right) & \mathcal{G}^s(p) = \bigcup_{k \ge 0} \mathcal{G}_k \\ &\cong \varinjlim(\mathcal{K}_*(\mathcal{C}^*(\mathcal{G}_k)), i_{k_*}) \\ &\cong \varinjlim(\mathcal{K}^*(Y), g!) & \mathcal{G}^k \sim_{\mathcal{M}.e.} Y \end{split}$$

where $g!: K^*(Y) \to K^*(Y)$ is the transfer map.

We can compute the unstable Putnam homology of (X, φ) as follows.

$$H^{u}_{*}(X,\varphi) \cong H_{*}(\mathcal{G}^{s}(p)) \qquad [PY]$$

$$\cong \varinjlim (H_{*}(\mathcal{G}_{k}), i_{k_{*}}) \qquad [FKPS]$$

$$\cong \varinjlim (H^{\mathcal{G}}_{*}(Y), \tilde{g}) \qquad \mathcal{G}_{k} \sim_{M.e.} Y$$

$$\cong \varinjlim (H^{*}(Y), g!) \qquad [CM]$$

where $g!: H^*(Y) \to H^*(Y)$ is the transfer map; in particular,

$$g! \circ g^* = \times n.$$

Let $Y = S^1 \subseteq \mathbb{C}$ and $g : S^1 \to S^1$ be $z \mapsto z^n$. Recall the transfer map $g! : H^*(S^1) \to H^*(S^1)$ satisfies $g! \circ g^* = \times n$.

$$\begin{array}{ll} H^0(S^1) = \mathbb{Z} & g^* = \mathrm{id} & \Rightarrow & g! = \times n \\ H^1(S^1) = \mathbb{Z} & g^* = \times n & \Rightarrow & g! = \mathrm{id} \end{array}$$

$$H_0^u(X,\varphi) \cong H_0(\mathcal{G}^s(p)) \cong \varinjlim(H^0(S^1),g!) \cong \varinjlim(\mathbb{Z},\times n) \cong \mathbb{Z}\left\lfloor \frac{1}{n} \right\rfloor$$
$$H_1^u(X,\varphi) \cong H_1(\mathcal{G}^s(p)) \cong \varinjlim(H^1(S^1),g!) \cong \varinjlim(\mathbb{Z},\operatorname{id}) \cong \mathbb{Z}$$

Example 2: 9-fold cover of the Klein bottle

 $g! \circ g^* = \times 9$

$$\begin{array}{lll} H^0(K) = \mathbb{Z} & g^* = \mathrm{id} & \Rightarrow & g! = \times 9 \\ H^1(K) = \mathbb{Z} & g^* = \times 3 & \Rightarrow & g! = \times 3 \\ H^2(K) = \frac{\mathbb{Z}}{2\mathbb{Z}} & g^* = \times 3 \equiv \mathrm{id} & \Rightarrow & g! = \times 3 \equiv \mathrm{id} \end{array}$$



$$H_0^u(X,\varphi) \cong \underline{\lim}(\mathbb{Z},\times 9) \cong \mathbb{Z}\left[\frac{1}{9}\right]$$
$$H_1^u(X,\varphi) \cong \underline{\lim}(\mathbb{Z},\times 3) \cong \mathbb{Z}\left[\frac{1}{3}\right]$$
$$H_2^u(X,\varphi) \cong \underline{\lim}\left(\frac{\mathbb{Z}}{2\mathbb{Z}},\mathsf{id}\right) \cong \frac{\mathbb{Z}}{2\mathbb{Z}}$$

General properties of $H^u_*(-)$

For Y a flat d-manifold and $g: Y \to Y$ an *n*-fold cover, the following hold for the associated Wieler solenoid (X, φ) :

- $H_0^u(X,\varphi) = \varinjlim(\mathbb{Z},\times n) = \mathbb{Z}\left[\frac{1}{n}\right]$
- If Y is orientable then $H^u_d(X, \varphi) = \mathbb{Z}$

Theorem (Epstein–Shub)

There is a $g: Y \to Y$ so that $T(H_*(\mathcal{G}^s(p))) = T(H^*(Y))$.

Theorem (Charlap)

For each prime p there exists a flat manifold Y with $H_1(Y) \cong \mathbb{Z} \oplus \mathbb{Z}/p\mathbb{Z}$.

Corollary

There exists a Smale space (X, φ) such that $\mathbb{Z}/p\mathbb{Z} \subseteq H_2^u(X, \varphi)$.

- [1] Charlap. Compact flat Riemannian manifolds: I, Annals., (1965).
- [2] Crainic, Moerdijk. A homology theory for étale groupoids, J. Reine Angew. Math., (2000).
- [3] Deeley, Goffeng, Mesland, Whittaker. Wieler solenoids, Cuntz-Pimsner algebras and K-theory, Ergod., (2018).
- [4] Epstein, Shub. Expanding endomorphisms of flat manifolds, Top., (1968).
- [5] Farsi, Kumjian, Pask, Sims. Ample groupoids: Equivalence, homology, and Matui's HK conjecture, Münster J. of Math., (2019).
- [6] Muhley, Renault, Williams. Equivalence and isomorphism for groupoid C*-algebras, J. Operator Theory, (1987).
- [7] Proietti, Yamashita. Homology and K-theory of dynamical systems. II, arXiv, (2021).
- [8] Putnam. C*-algebras from Smale spaces, Ca. J. of Math., (1996).
- [9] Putnam. A homology theory for Smale spaces, Memoirs, (2014).
- [10] Shub. Endomorphisms of compact differentiable manifolds, Am. J. of Math., (1969).
- [11] Wieler. Smale spaces via inverse limits, Ergod., (2014).